

Temposonics®

Magnetostrictive Position Sensors

M-Series Analog

Temposonics MH Measuring length 50 - 2500 mm

PRELIMINARY

Compact Sensor for Mobile Hydraulics

- Linear, Absolute Measurement in Hydraulic Cylinders
- Contactless Sensing with Highest Durability
- Minimum Dimensions for Compact Mobile Hydrocylinders
- Replacing Potentiometers and Inductive Position Sensors
- Superior Accuracy: Linearity Tolerance better 0,04 %
- Repeatability 0,005 %
- Direct Analog Displacement Output: Current and Voltage
- Power Supply: 12 / 24 VDC
- EMC: Immunity against electromagnetic HF-fields up to 200 V/m
- Independent from Hydraulic Liquid



The absolute Temposonics® linear position sensors are based on the MTS developed magnetostrictive measurement principle. That combines various magneto-mechanical effects and uses the physical height precise speed-measurement of an ultrasonic wave (torsion pulse in its sensor element) for position detecting. Sensor integrated signal processing transforms the measurements directly into market standard outputs. The contactless principle - an external movable magnet marks the position - eliminates the wear, noise and erroneous signal problems and guarantees the best durability without any recalibration.

Temposonics[®] MH, the compact stainless steel position sensor is designed for installation into hydraulic cylinders, specifically for use in clevis head mobile cylinders or any space limited cylinder applications. 1. The sensor head, a robust housing with built-in electronics. 2. The pressure-proof sensor pipe with flange protects the internal sensing element, the waveguide system. It fits into the bored piston rod. 3. The position magnet, only moving part is mounted on the piston bottom. This permanent magnet travels wearfree and contactless along the stationary sensor tube. Its magnetic field starts the measurement signal through the sensor's rod wall.



Analog

Designed for the mobile world

M-Series sensors were designed with the "mobile" world in mind, and have been validated in the field by customers worldwide. Performance is second to-none; high accuracy, 200 V/m EMI, position output. Ruggedness is "designed in"; 100 g shock and 25 g vibration rating. Cable and wire options are sized for direct connection to industry proven connectors. The model MH sensor can be fully sealed and embedded in a cylinder to ensure a long operating life.

Technical Data

Input	
Measured Variables:	Displacement
Measuring Range:	50 - 2500 mm in 5 mm steps
Output	
Voltage:	0 - 5 VDC / 0,25 4,75 / 0,5 4,5 VDC; (Controller input resistance RL: \ge 10 kOhm, short circuit-proof, electric strength up to 28 Vdc)
Current:	4 - 20 mA load resistor ≤ 250 0hm with 12 V power supply, load resistor ≤ 500 0hm with 24 V power supply)
Accuracy	
Resolution:	0,1 mm
Linearity, uncorrected:	< ± 0,04 % F.S. (Minimum ± 0,100 mm)
Repeatability:	< ± 0,005 % F.S.
Update Frequency:	500 Hz
Ripple:	< 0,02 % F.S.
Set point tolerance:	± 0,7 mm
Operating conditions	
Mounting Position, Sensor: Magnet Speed:	Any orientation
Operating Temperature:	
Dew Point Humidity:	0.0% ral humidity no condensation
Sealing:	
Rod Pressure Bating:	200 har 450 har neek pressure for 7 mm rod diameter
nou Fressure nating.	450 bar, 450 bar pack pressure for 7 min fod diameter
Shook Pating:	100 dai, roo dai peak pressure foi no min fou diameter
Vibration Dating:	
EMC-Toot	ISO 14020 Articultural and foract machine
LIVIO-TESI.	
	ISO 7037-77273 Rudu Velicites
	EMC for raiway vohice DN EN 50121-2.2
Form factor Material	Livio foi raliway venicies Din Lin 30121-3-2
Material Sansor:	Staiplass staal 1 4205 / AISL 204
Magnat Type:	Diam magnet
Installation	ning magnet
Mounting	Losa fit flanga (1.48 mm
Electrical connections	Lose in hange 9 40 mm
Connection Type:	Distailed DLD cable 2 wires
Input Voltago:	$\frac{12}{10} \frac{10}{10} 10$
Pipple:	$(2/24)U_0(10-52)$
Current Drain:	
Current Dialli.	< 00 IIIA 500 VDC (0 V ground to machine ground)
Electric Streligtil.	
Pularity Protection:	
overvollage Protection:	UD 10 30 ADC

Temposonics-MH - High Pressure Compact Sensor Measuring Range 50 - 2500 mm.

Temposonics-MH, the new compact stainless steel position sensor is designed for installation into hydraulic cylinders, specifically for use in clevis head mobile cylinders or any space limited cylinder applications.

MH type sensors are ideal choices for a wide range of standard hydraulic cylinders. Magnetostrictive displacement sensors, high quality cylinders and precise control valves form ideal driving systems for technically demanding of mobile hydraulics.

Simple mechanics

The extremely rugged sensor consist of 3 main parts

- The sensor head, a robust housing with built-in electronics.
- The pressure-proof sensor pipe (up to 450 bar) with flange protects the internal sensing element, the waveguide system. It fits into the bored piston rod.
- The position magnet, only moving part is mounted into the piston bottom. This permanent magnet travels wearfree and contactless along the stationary sensor tube. Its magnetic field starts the measurement signal through the sensors rod wall.







Ø 23

Cable exit option

Mating cable Ø 5 mm

Position Magnets



Ring magnet OD33 Part No. 201 542-2

PA-Ferrit-GF20 Gewicht ca. 14g Operating temperature: -40... +100°C Surface pressure max. 40 N/mm² in axial direction Fastening Torque for M4 screws max. 1 Nm





Composite PA-Ferrite-GF20 Weigth ca. 14g Operating temperature: -40...+100°C Surface pressure max. 40 N/mm² in axial direction



Ring magnet OD17,4 Part No. 401 032

Composite PA-Ferrite Weigth ca. 10g Operating temperature: -40 ... +100°C Surface pressure max. 10 N/mm² in axial direction

Measurement in mm. Technical alterations reserved.



The robust Temposonics Model MH sensor's new stainless-steel position sensor is designed for direct stroke measurement in standard compact hydraulic cylinders. The Temposonics Model MH sensor can be installed from the head side or the rod side of the cylinder depending on the cylinder design.

Sensor installation

The method of installation is entirely dependent on the cylinder design. While the most common method of installation is from the rod side of the cylinder, installation from the head side of the cylinder is also possible. In both installation methods, the sensor seals the cylinder by using an O-Ring and backup ring which is installed on the sensor housing.

Magnetizable material



Position magnet 🔲 nonferrous spacer

Non-magnetizable material



Detail Flange housing



Installation Versions



Example 2 (rod side installation) The sensor should be fixed with set screw



e.g. retaining with set screw DIN 913 M5x10 (with flat point!) maximum torque 0,5 Nm



Installation Notes

• Use a non-ferrous circlip to prevent wear on the magnet and the sensor pipe.

• The bore in the piston rod is dependent on hydraulic pressure

and piston velocity etc. The minimum drilling must be 10 (7 mm rod) or 13 mm (10 mm rod).

Cable outlet

PUR-cable, 3 x 0,5 mm², Ø 5 mm, flexible, oil resisting



Single wire outlet



Wiring

Wiring

Wire color	Signal
brown	+12/24 VDC
white	DC Ground (0V)
green	Output: Voltage range

Connector system (IP 69K)







Pin	Signal	
1	N.C.e	
2	+12/24 VDC	
3	DC Ground (0V)	
4	Output	





400 633	
St C0 9131 S06	

Accessories see below.

Accessories (selection)	Part No.
Ring magnet OD33	201 542-2
Ring magnet OD25,4	400 533
Ring magnet OD17,4	401 032
Magnet spacer OD32	400 633
(use with magnet part no. 201 542-2)	
6 pin wall mount receptacle, male	St C0 9131 S

A01 = 4 - 20 mA

V10 = 0 - 5 V **V11** = 0,25 - 4,75 V **V12** = 0,5 - 4,5 V

Input Voltage 3 = +12/24 VDC Signal Output

T05A = 0,5 m min. length **T99A** = 9,9 m max. length

Cable exit: T_ _A = PUR cabe, 3 conductors, 0,5 mm², pigtailed, 0,1 m increments

N_ E = 4 single wires, 0,5 mm² with system connector M12 IP69k, 4 pin, 10 mm increments N07E = 70 mm min. wire length N17E = 170 mm max. wire length (Longer wires on request / min. order quantities)

N_ _A = 3 single wires, 0,5 mm², 10 mm increments N10A = 100 mm (min. wire length)

N20A = 200 mm **N99A** = 990 mm

Measuring Range (Order Length) 0050 - 2500 mm in 5 mm steps **Connection Type** Wire exit:

Style

Temposonics

MH = Hydraulic rod

 $C = Flange housing \emptyset 48 mm / Rod-\emptyset 10 mm$ \mathbf{D} = Flange housing Ø 48 mm / Rod-Ø 7 mm

MH

Μ

(available on request)

R = Flange housing Ø 48 mm / Rod-Ø 10 mm

with rod end plug, threaded hole M4

3

Temposonics-MH

Scope of Delivery

- Position Sensor



- Backup-Ring

Pls. order magnets separately.

Temposonics-MH Analog

www.mtssensor.com www.temposonics-shop.de



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